SINEX - Solution (Software/technique) INdependent EXchange Format
Version 2.10 (September 15, 2006)

INTRODUCTION

The SINEX acronym was suggested by Blewitt et al. (1994) and the first versions, 0.04, 0.05, 1.00 evolved from the work and contributions of the SINEX Working Group of the IGS. The IGS Analysis Centres and Associated Analysis Centres use the SINEX format for their weekly solutions since mid 1995. Although the SINEX format was developped by the IGS, the ILRS and IVS decided to use it for their pilot projects as well because SINEX was designed to be modular and general enough to handle GPS as well as other techniques. To meet all the requirements for SLR and VLBI solutions some new elements and more detailed specifications were added by the ILRS Analysis Working Group and by the IVS. During 2002, these extensions were merged with the previous SINEX version 1.00 to get a unique format definition for all space geodetic techniques. After an intensive discussion with the IGS Reference Frame Working Group chaired by R. Ferland, the ILRS Analysis Coordinator R. Noomen and the ILRS Analysis Working Group, the IVS Analysis Coordinator A. Nothnagel and Z. Altamimi from the ITRF section of IGN, the version called SINEX 2.00 could be finalized. The latest changes to version 2.10 are mainly due to an extended list of parameters and the demands of GALILEO.
The changes between the different versions (1.00, 2.00, 2.01, 2.10) are given in the next section of this document. The complete and detailed format definition can be seen in APPENDIX I, and the relevant least squares adjustment formulas with their relations to the SINEX format are summarized in APPENDIX II.

CHANGES FROM VERSION 2.01 TO 2.10

1) The version number in the header line changes to 2.10.

2) The epoch 00:000:00000 is now explicitly allowed for the SINEX template created at the IGS Central Bureau.

3) The list of allowed parameter types has increased. As additional parameters you can include in the SINEX file:

- CN = Normalized spherical harmonic coefficient of the Earth’s gravity field (cosine term)
- SN = Normalized spherical harmonic coefficient of the Earth’s gravity field (sine term)
- NUT_X = Nutation angle DELTA_X (correction to a priori model; new paradigm)
- NUT_Y = Nutation angle DELTA_Y (correction to a priori model; new paradigm)
- NUTR_X = Linear drift for nutation angle DELTA_X
- NUTR_Y = Linear drift for nutation angle DELTA Y

The new paradigm for the nutation angles is documented in Capitaine et al. (2002) or McCarthy and Petit (2004).
The degree and order of the spherical harmonic coefficients is stored in the columns ‘Site Code’ and ‘Solution ID’, respectively.

4) Following the actual usage of the nutation parameters the SINEX specification is adapted: the nutation parameters (NUT_LN, NUT_OB, NUT_X, NUT_Y, NUTPLN, NUTPOB, NUTP_X, NUTP_Y) should no longer represent the total nutation angles but they represent corrections to the a priori model used in the analysis. The information about the a priori model is provided in the block NUTATION/DATA.
Furthermore, the unit recommended for the nutation angles is changed to [mas] and [mas/d] instead of [rad] and [rad/d], respectively.

5) In order to prepare the SINEX format for the inclusion of Galileo observations, the description is extended for the ‘Site Code’, the ‘Point Code’, the ‘PRN’ in the SATELLITE/ID block and the ‘Frequency Code’ in the SATELLITE/PHASE_CENTER block. The coding of the frequencies is aligned to the RINEX 3.00 standard.
Additionally, a new block SITE/GAL_PHASE_CENTER is included. The structur of this new block is similar to the GPS counterpart SITE/GPS_PHASE_CENTER. But as the information

for more than two frequencies has to be stored for Galileo, the new block is defined to have three lines per antenna, each with the phase center offsets for two frequencies, and the order of the frequencies is predefined.

CHANGES FROM VERSION 2.00 TO 2.01

1) The version number in the header line changes to 2.01.

2) The list of allowed estimated parameter types has increased. As additional parameters you can include in your solution:

- SATA_Z = satellite antenna Z offset [m]
- SATA_X = satellite antenna X offset [m]
- SATA_Y = satellite antenna Y offset [m]

3) Due to these new parameters a character defining antenna parameters ('A') was added to the field 'Solution Contents' in the HEADER LINE and in the block INPUT/HISTORY. The character 'A' may also be used for VLBI antenna parameters.

4) Two new blocks were added:

- SATELLITE/ID (Recommended for GNSS, if available)
- SATELLITE/PHASE_CENTER (Mandatory for GNSS, if satellite antenna offsets are not estimated)

CHANGES FROM VERSION 1.00 TO 2.00

1) The version number in the header line changes to 2.00.

2) The list of allowed estimated parameter types has increased. As additional parameters you can include in your solution:

- XGC \
- YGC - = coordinates of the geocenter [m]
- ZGC /
- RS_RA = right ascension of a radio source [rad]
- RS_DE = declination of a radio source [rad]
- RS_RAR = rate of right ascension of a radio source [rad/y]
- RS_DER = rate of declination of a radio source [rad/y]
- RS_PL = radio source parallax [rad]
- NUT_LN = nutation total in longitude [rad]
- NUT_OB = nutation total in obliquity [rad]
- NUTRLN = nutation rate in longitude [rad/d]
- NUTROB = nutation rate in obliquity [rad/d]
- TGNWET = troposphere gradient in north for the wet part [m]
- TGNDRY = troposphere gradient in north for the dry part [m]
- TGNTOT = total troposphere gradient in north (wet + dry part) [m]
- TGEWET = troposphere gradient in east for the wet part [m]
- TGEDRY = troposphere gradient in east for the dry part [m]
- TGETOT = total troposphere gradient in east (wet + dry part) [m]
- AXI_OF = VLBI antenna axis offset [m]
- RBIAS = range bias [m]
- TBIAS = time bias [ms]
- SBIAS = scale bias [ppb]
- ZBIAS = troposphere bias in zenith [m]

The parameters LODR and UTR (LOD and UT1-UTC reduced for the short periodic terms up to 35 days) are no official SINEX parameters and should not be used.
The coordinates of geocenter already appear in some IGS solutions, so we decided to define these parameters as officially allowed.
The coordinates of radio sources (right ascension, declination) and their rates, the parallax of radio sources, the nutation parameters and their rates, the troposphere

gradients and the antenna axis offsets are new parameters requested for VLBI solutions.
The four bias parameters are taken from the ILRS implementation of SINEX.

3) Due to these new parameters the field 'Solution Contents' in the HEADER LINE and in the block INPUT/HISTORY must be changed.

All parameters belonging to the stations are summarized in only one character:
'S' = station coordinates (STAX, STAY, STAZ),
station velocities (VELX, VELY, VELZ),
all four bias parameters (RBIAS, TBIAS, SBIAS, ZBIAS),
geocenter coordinates (XGC, YGC, ZGC).
That means, the character 'X' for station coordinates and 'V' for station velocities are dropped.

A new character is defined for all parameters belonging to the celestial reference frame:
'C' = right ascension and declination of the radio sources (RS_RA, RS_DE),
rates for right ascension and declination of the radio sources (RS_RAR, RS_DER),
parallax of radio sources (RS_PL).

The other new parameters can be attached easily to the existing characters of SINEX version 1.00:
'T' = for all troposphere parameters (including the new parameters for the troposphere gradients TGNWET, TGNDRY, TGNTOT, TGEWET, TGEDRY, TGETOT),
'E' = for all earth orientation parameters (including the new nutation parameters NUT_LN, NUT_OB, NUTRLN, NUTROB).

The orbit parameters 'O' are not changed.

4) The block SOLUTION/STATISTICS is now RECOMMENDED if the requested values are available because for a further combination of solutions it is necessary to have the complete statistical information.

The preference is given to the original values like 'NUMBER OF OBSERVATIONS' and 'NUMBER OF UNKNOWNS' instead of 'DEGREE OF FREEDOM'.

The 'NUMBER OF OBSERVATIONS' should represent only the number of 'real' observations.

A new value became necessary if unconstrained normal equations are stored because the variance factor contains the constraints of the solution. Therefore the weighted square sum of the vector 'observed minus computed' should be given in the SOLUTION/STATISTICS block to become independent of the influence of the constraints on the variance factor: (o-c)‘ P (o-c), where (o-c) represents the vector 'observed minus computed' and P denotes the weigth matrix. This new value can be stored under the name
WEIGHTED SQUARE SUM OF O-C

5) The list of allowed parameter types in the block SOLUTION/APRIORI is extended following some IGS solutions: if you apply inner constraints to your solution you can add the constrained transformation parameters to the SOLUTION/APRIORI block.

That means for the particular fields of this block:

- Parameter Type:

TX, TY, TZ	for translation restrictions in x, y and z direction
RX, RY, RZ	for rotation restrictions around the x, y and z axis
SC	for scale restriction
TXR, TYR, TZR	for restrictions on the rates of the translation in x, y and z
RXR, RYR, RZR	for restrictions on the rates of the rotation around the x, y and z axis
SCR	for restriction on the rate of the scale

- The fields Site Code, Point Code, Solution ID are filled with '-'

- Time:
the reference epoch of the inner constraints

- Parameter Units:
 m   for translation parameters, i.e. [m]
 mas   for rotation parameters, i.e. [mas]
 ppb   for the scale, i.e. [ppb]
 m/y   for the rates of translation parameters, i.e. [m/y]
 ma/y for the rates of rotation parameters, i.e. [mas/y]
 pb/y for the rate of the scale, i.e. [ppb/y]

- Constraint Code:
0 for tight constraints

- Parameter Apriori:
the value on which you constrained the transformation parameter or its rate for the transformation of your solution according to the apriori reference frame
(e.g. if the apriori reference frame represents the desired reference frame for your solution the apriori parameters are 0.0)

- Parameter Standard Deviation:
the sigma you choose for constraining the particular transformation parameter or its rate

To decide which stations were contributing to the inner constraints, the appropriate station parameters (coordinates and velocities if the rates are given as well) must be given in the block SOLUTION/APRIORI as well and should contain a '1' in the field 'CONSTRAINT CODE'.

6) With the new SINEX version the delivery of normal equations will be defined more precisely. We have now three possibilities include normal equation systems in the SINEX file:

a) In principle it was already possible in version 1.00 to store normal equation matrices in the two SOLUTION/MATRIX blocks (ESTIMATE and APRIORI) if you use matrix type INFO. And together with the two vectors in SOLUTION/ESTIMATE and SOLUTION/APRIORI you are able to reconstruct the original (reduced) normal equation system without constraints. But this procedure of removal the constraints and compute the right hand side of the normal equation system is always a little bit critical, and in addition to that problem, the procedure depends on the solution vector given in SOLUTION/ESTIMATE.

For a further combination of several solutions there would be less problems if the original normal equation system without any constraints can be stored directly in the SINEX file. In that case you have the advantage that the constraints applied in the individual solutions (SOLUTION/MATRIX_APRIORI) and the resulting solution vector (SOLUTION/ESTIMATE) have no influence on the combination. These considerations led to two other possibilities of storing normal equations in the SINEX file, but for both we had to introduce two new blocks for the original normal equation system:
- SOLUTION/NORMAL_EQUATION_VECTOR
This block contains the vector of the right hand side of the reduced normal equation system
b = A' P l
  where
  A' is the transposed of the Jacobi-Matrix,
  P   is the weight matrix of the observations and
  l   is the vector observed minus computed with apriori values.
- SOLUTION/NORMAL_EQUATION_MATRIX
This block contains the reduced normal equation matrix WITHOUT constraints (i.e. the 'free' / original solution):
N = A‘ P A
The structure of this block is similar to the other two MATRIX blocks.
The indices of both new blocks must be consistent with the indices in SOLUTION/ESTIMATE.

With these two additional blocks the second and third possibility of storing normal equations look as follows:

b) You store the complete information about your solution in the following blocks:

- original normal equation matrix N = A‘ P A : SOLUTION/NORMAL_EQUATION_MATRIX
- vector of right hand side of original normal equation b = A‘ P l : SOLUTION/NORMAL_EQUATION_VECTOR
- apriori values of the unknown parameters x0: SOLUTION/APRIORI
- normal equation matrix of applied constraints in your solution dN: SOLUTION/MATRIX_APRIORI
- resulting unknown parameters of the constrained solution x = x0 + inv(N + dN) b : SOLUTION/ESTIMATE

The advantage of this method is the availability of the whole information, i.e. the original normal equation can be used for a further combination without any problems of constraints removal like in method a), and other users who are interested in the parameters of the constrained solution itself can take the vector in SOLUTION/ESTIMATE.
A problem might occur when generating such a SINEX file because you need both, the original normal equation system as well as the solution estimate (as in case a)) and in most software packages the normal equation matrix might already be inverted at the time when you have the solution estimate available.

c) The third possibility is storing only the original normal equation system in the SINEX file, i.e.
- original normal equation matrix N = A‘ P A : SOLUTION/NORMAL_EQUATION_MATRIX
- vector of right hand side of original normal equation b = A‘ P l : SOLUTION/NORMAL_EQUATION_VECTOR
- apriori values of the unknown parameters x0: SOLUTION/APRIORI

For a further combination with other solutions this would be enough information and there wouldn’t be any problems with constraints removal.
On the other hand the documentation of the estimated parameters is missing.

To reconstruct the statistical information about the original solution for the last two possibilities (points b) and c)) it is necessary to store the weighted square sum of the vector observed minus computed, i.e. l‘ P l in the SOLUTION/STATISTICS block because only this part of the variance factor is independent of the constrained solution and can be taken for a combination
(v‘ P v = l‘ P l – (x – x0)‘ b):
WEIGHTED SQUARE SUM OF O-C
(see as well point 4) of the changes from version 1.00 to 2.00)

7) For more clearness and with regards to a good documentation how the solution in SOLUTION/ESTIMATE was created, the block SOLUTION/APRIORI is now mandatory.
The block SOLUTION/MATRIX_APRIORI is only mandatory if the matrix in SOLUTION/MATRIX_ESTIMATE contains some constraints.

If you deliver normal equations in your SINEX file some more blocks are mandatory, depending on the method of storing normal equations:
For method 6a)
- SOLUTION/MATRIX_APRIORI (INFO type)
- SOLUTION/MATRIX_ESTIMATE (INFO type)
- SOLUTION/STATISTICS (#observations, #unknowns, weighted square sum of o-c)

For method 6b)
- SOLUTION/MATRIX_APRIORI
- SOLUTION/NORMAL_EQUATION_MATRIX
- SOLUTION/NORMAL_EQUATION_VECTOR
- SOLUTION/STATISTICS (#observations, #unknowns, weighted square sum of o-c)

For method 6c)
- SOLUTION/NORMAL_EQUATION_MATRIX
- SOLUTION/NORMAL_EQUATION_VECTOR
- SOLUTION/STATISTICS (#observations, #unknowns, weighted square sum of o-c)

8) Besides the new blocks for normal equations we have introduced some other new blocks in the SINEX format 2.00:

- NUTATION/DATA:
to store the information about the nutation model used in the analysis;
This block contains two fields: one for the name of the nutation model and one for some comments.

- PRECESSION/DATA:
to store the information about the precession model used in the analysis;

This block contains two fields: one for the name of the precession model and one for some comments.

- SOURCE/ID:
to provide information about the radio sources observed with VLBI;
There are 3 fields for source names: the Source Code (used for SINEX internal referencing), the IERS designation and the ICRF designation.

- BIAS/EPOCHS:
important if bias parameters are included in the solution (from SLR solutions)

9) The matrix type SRIF (for Square Root Information Filter Matrix) in the two blocks SOLUTION/MATRIX_APRIORI and SOLUTION/MATRIX_ESTIMATE is no longer allowed.

10) The longitude sign definition in the SITE/ID block is redefined according to the ISO6709 definition (that is the way the information was already stored in most of the SINEX files):
- positive longitudes have to be used for east direction with respect to the Greenwich meridian
- following the ISO6709 specification, the range of longitude should be [-180° +180°[

11) The value "-----" in the field 'Antenna Serial Number' of the SITE/GPS_PHASE_CENTER block is redefined:
it signifies that the phase center offsets for L1 and L2 that are given in the following columns apply to ALL antennas of the same type that is indicated in the field 'Antenna Type'.
As a consequence, if the phase center offsets for one antenna name and the given model are the same for all antenna serial numbers, it is enough to store only one data line (with "-----" for the 'Antenna Serial Number') in the SITE/GPS_PHASE_CENTER block for each antenna type that appears in the SITE/ANTENNA block.

SINEX SYNTAX

SINEX is an ASCII file with lines of 80 chars or less. It consists of a number of blocks which are mutually referenced (related) through station codes/names, epochs and/or index counters. Some blocks consist of descriptive lines (starting in Col.2) and/or fixed format fields with numerous headers and descriptive annotations.

The first line is MANDATORY and must start with "%" in col 1, and contains information about the agency, file identification, solution spans, techniques, type of solution, etc. (for more details see the Appendix I or II). The last line ends with "%ENDSNX".

The SINEX format consists of a number BLOCKS which start with "+" in the first col. followed by a standardized block labels, and each block ends with "-" and the block label. Each block data starts in the column 2 or higher. Blocks can be in any order, provided that they start with (+) and end with (-) block labels. The first header line and most blocks are related through epochs or time stamps in the following format: YY:DOY:SECOD YY-year; DOY- day of year; SECOD -sec of day; E.g. the epoch 95:120:86399 denotes April 30, 1995 (23:59:59UT). The epochs 00:00:00000 are allowed in all blocks, except the first header line if the SINEX file is an output of a data analysis (in case of a SINEX template the epoch 00:00:00000 is allowed in the header line as well) and default into the start or end epochs of the first header line which must always be coded. This is particularly useful for some blocks, such as the ones related to hardware, occupancy, which should be centrally archived by IGSCB with 00:00:00000 as the end (current) epochs, and which should be readily usable by ACs for SINEX and other analysis/processing as official (authoritative) IGS information.

COMMENT lines starts with "*" in Col. 1 and can be anywhere within or outside a block, though for the clarity sake, beginning and ends of blocks are preferable. For increased portability, the floating number exponent of "E" should be used rather than "D" or "d" which is not recognized by some compiler/installations.

Fields not coded should be filled with "-" characters to allow efficient row and column format readings.

The most important blocks are the SOLUTION blocks. They are in fixed format (For more information on the format, see APPENDIX I).
The mandatory SOLUTION blocks depend on the contents of the SINEX file.
If you deliver variance-covariance matrices or correlation matrices in your SINEX files the blocks
- SOLUTION/ESTIMATE
- SOLUTION/APRIORI
- SOLUTION/MATRIX_ESTIMATE
are mandatory.
The block SOLUTION/MATRIX_APRIORI is only mandatory if the matrix in SOLUTION/MATRIX_ESTIMATE contains some constraints.
Important but not mandatory (though STRONGLY RECOMMENDED if available for IERS purposes) is the block SOLUTION/STATISTICS, especially the information about the number of observations, the number of unknowns and the variance factor.

If you deliver normal equations in your SINEX file the mandatory SOLUTION blocks depend on the method of storing normal equations:
For method 6a)
- SOLUTION/APRIORI
- SOLUTION/ESTIMATE
- SOLUTION/MATRIX_APRIORI (INFO type)
- SOLUTION/MATRIX_ESTIMATE (INFO type)
- SOLUTION/STATISTICS (#observations, #unknowns, weighted square sum of o-c)
For method 6b)
- SOLUTION/APRIORI
- SOLUTION/ESTIMATE
- SOLUTION/MATRIX_APRIORI
- SOLUTION/NORMAL_EQUATION_MATRIX
- SOLUTION/NORMAL_EQUATION_VECTOR
- SOLUTION/STATISTICS (#observations, #unknowns, weighted square sum of o-c)
For method 6c)
- SOLUTION/APRIORI
- SOLUTION/NORMAL_EQUATION_MATRIX
- SOLUTION/NORMAL_EQUATION_VECTOR
- SOLUTION/STATISTICS (#observations, #unknowns, weighted square sum of o-c)

Storing the (reduced) normal equation system in one of the possible ways described before is encouraged for combination research purposes within the IERS to avoid the critical step of constraints removal.

The scale of estimated and apriori standard deviations can, in principle, be arbitrary (note even apriori scaling is arbitrary, depending on the observation weighting). However, both estimated and apriori standard deviations (and the corresponding matrices) MUST use the same scaling (i.e. variance) factor stored in the block SOLUTION/STATISTICS. Otherwise the apriori information cannot be rigorously removed to form free solutions (e.g. normal matrices). Scaling between different SINEX solutions is beyond the SINEX format and must be dealt with at the combination/analysis stage.

REFERENCES

- Blewitt, G., Y. Bock and J. Kouba: "Constraining the IGS Polyhedron by Distributed Processing", workshop proceedings : Densification of ITRF through Regional GPS Networks, held at JPL, Nov30-Dec 2, 1994, pp. 21-37.

- Capitaine, N., D. Gambis, D.D. McCarthy, G. Petit, J. Ray, B. Richter, M. Rothacher, E.M. Standish and J. Vondrak (eds.): Proceedings of the IERS Workshop on the Implementation of the new IAU Resolutions. Held at the Observatoire de Paris, Paris, France, 18-19 April 2002. IERS Technical Note No. 29. Verlag des Bundesamts fuer Kartographie und Geodaesie, Frankfurt/Main, 2002.

- McCarthy, D.D. and G. Petit (eds.): IERS Conventions (2003). IERS Technical Note No. 32. Verlag des Bundesamts fuer Kartographie und Geodaesie, Frankfurt/Main, 2004.

- SINEX version 1.00 description:
  ftp://igscb.jpl.nasa.gov/igscb/data/format/sinex.txt

- ILRS implementation of the SINEX format (R.Noomen, V.Husson):
  ftp://ilrs.gsfc.nasa.gov/ilrs/sinex_file_description.html
  http://ilrs.gsfc.nasa.gov/awg_min_toulouse2001.html

- Proposal for extending the SINEX 1.0 format for geodetic and astrometric VLBI:
  ftp://giub.geod.uni-bonn.de/vlbi/IVS-AC/sinex_proposal.html

- Requirements for SINEX solutions contributing to the ITRF97:
  ftp://lareg.ensg.ign.fr/ITRF/ITRF-SINEX.html

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Version 2.10 (September 15, 2006)

A P P E N D I X I

S I N E X

V E R S I O N 2 . 1 0

D E T A I L E D F O R M A T D E S C R I P T I O N

1. Introduction

This document describes the Software Independent Exchange (SINEX) format. It started in early 1995 with an effort by a number of IGS participants and it was designed to be easily extended. For the new IERS structure, operational since January 1, 2001, and due to the use of SINEX by the ILRS (pilot project 'positioning and earth orientation') and the IVS as well, some extensions were made with the purpose to have a unique format description for all techniques.

2. Data Structure

Each SINEX line has at most 80 ASCII characters.
The SINEX file is subdivided in groups of data called blocks. Each block is enclosed by a header and trailer line. Each block has a fixed format. The blocks contain information on the file, its input, the sites and the solution. All elements within a line are defined. A character field without information will have "-"s within its field and a missing numerical element will have a value of 0 within its field. Therefore the SINEX file is accessible "column-wise" as well as "line-wise". Character fields should be left hand justified whenever applicable.

The first character of each line identifies the type of information that the line contains. Five characters are reserved. They have the following meaning when they are at the beginning of a line, they identify:

Character	Definition
"%"	Header and trailer line,
"*"	Comment line within the header and trailer line,
"+"	Title at the start of a block
"-"	Title at the end of a block
" "	Data line within a block

No other character is allowed at the beginning of a line!

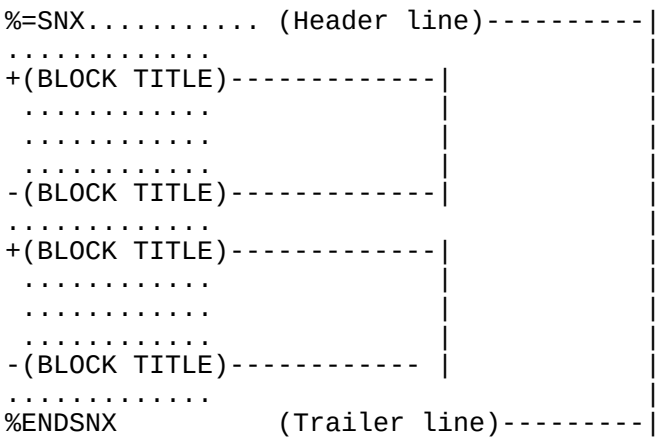
A SINEX file must start with a header line and ends with a footer line.

The following blocks are defined:

FILE/REFERENCE
FILE/COMMENT
INPUT/HISTORY
INPUT/FILES
INPUT/ACKNOWLEDGEMENTS
NUTATION/DATA
PRECESSION/DATA
SOURCE/ID
SITE/ID
SITE/DATA
SITE/RECEIVER
SITE/ANTENNA
SITE/GPS_PHASE_CENTER
SITE/GAL_PHASE_CENTER
SITE/ECCENTRICITY
SATELLITE/ID
SATELLITE/PHASE_CENTER
BIAS/EPOCHS
SOLUTION/EPOCHS
SOLUTION/STATISTICS
SOLUTION/ESTIMATE
SOLUTION/APRIORI
SOLUTION/MATRIX_ESTIMATE {p} {type}
SOLUTION/MATRIX_APRIORI {p} {type}
SOLUTION/NORMAL_EQUATION_VECTOR
SOLUTION/NORMAL_EQUATION_MATRIX {p}

Where: {p} L or U
{type} CORR or COVA or INFO

These block titles are immediately preceded by a "+" or a "-" as they mark the beginning or the end of a block. The block titles must be in capital letters. After a block has started(+) it must be ended(-) before another block can begin. The general structure is as follows:



Most fields within a SINEX line are separated by a single space. In the following sections, each SINEX line is defined by its field name, a general description and the (FORTRAN) format.

A comment line (not to be confused with the FILE/COMMENT Block) can be written anywhere within the header and the footer line. All comment lines must start with a "*" in the first column. With the use of this character information can be hidden from the software reading the file without deleting it from the file. A comment line is defined as follows:

COMMENT DATA LINE

Field	Description	Format
Comment	Any general comment relevant to the SINEX file.	1H*,A79
		80

Some fields are found in several blocks. To keep the description short, they are described in detail here, and will be referred to in the sections with additional information added when necessary. The fields defined below will be referenced to by putting them within square brackets [] when encountered in the following sections.

Field	Description	Format
Time	YY:DDD:SSSSS. "UTC" YY = last 2 digits of the year, if YY <= 50 implies 21-st century, if YY > 50 implies 20-th century, DDD = 3-digit day in year, SSSSS = 5-digit seconds in day.	I2.2, 1H:,I3.3, 1H:,I5.5
Constraint Code	Single digit indicating the constraints: 0-fixed/tight constraints, 1-significant constraints, 2-unconstrained.	A1
Parameter Type	Type of parameter. List of allowed parameters and the units provided: STAX - station X coordinate, m	A6

| STAY - station Y coordinate, m|
| STAZ - station Z coordinate, m|
| VELX - station X velocity, m/y|
| VELY - station Y velocity, m/y|
| VELZ - station Z velocity, m/y|
| XGC - geocenter X coordinate, m|
| YGC - geocenter Y coordinate, m|
| ZGC - geocenter Z coordinate, m|
| RS_RA - radio source right ascension, rad|
| RS_DE - radio source declin., rad|
| RS_RAR - radio source right ascension rate, rad/y|
| RS_DER - radio source declination rate, rad/y|
| RS_PL - radio source parallax, rad|
| LOD - length of day, ms|
| UT - delta time UT1-UTC, ms|
| XPO - X polar motion, mas|
| YPO - Y polar motion, mas|
| XPOR - X polar motion rate, mas/d|
| YPOR - Y polar motion rate, mas/d|
| NUT_LN – nutation correction in longitude, mas|
| NUT_OB – nutation correction in obliquity, mas|
| NUTRLN - nutation rate in longitude, mas/d|
| NUTROB - nutation rate in obliquity, mas/d|
| NUT_X - nutation correction X, mas|
| NUT_Y - nutation correction Y, mas|
| NUTR_X – nutation rate in X mas/d|
| NUTR_Y – nutation rate in Y mas/d|
| SAT__X - Satellite X coord., m|
| SAT__Y - Satellite Y coord., m|
| SAT__Z - Satellite Z coord., m|
| SAT_VX - Satellite X velocity, m/s|
| SAT_VY - Satellite Y velocity, m/s|
| SAT_VZ - Satellite Z velocity, m/s|
| SAT_RP - Radiation pressure, |
| SAT_GX - GX scale, |
| SAT_GZ - GZ scale, |
| SATYBI - GY bias, m/s2|
| TROTOT - wet + dry Trop. delay, m|
| TRODRY - dry Trop. delay, m|
| TROWET - wet Trop. delay, m|
| TGNTOT – troposphere gradient in north (wet + dry), m|
| TGNWET – troposphere gradient in north (only wet), m|
| TGNDRY – troposphere gradient in north (only dry), m|
| TGETOT - troposphere gradient in east (wet + dry), m|
| TGEWET – troposphere gradient in east (only wet), m|
| TGEDRY – troposphere gradient in east (only dry), m|
| RBIAS - range bias, m|
| TBIAS - time bias, ms|
| SBIAS - scale bias, ppb|
| ZBIAS - troposphere bias at zenith, m|
| AXI_OF – VLBI antenna axis offset, m|
| SATA_Z – sat. antenna Z offset m|
| SATA_X – sat. antenna X offset, m|
| SATA_Y – sat. antenna Y offset, m|
| CN - spherical harmonic |

	coefficient C_nm SN - spherical harmonic coefficient S_nm	
Site Code	- For stations: Call sign for a site.(It should be consistent with ITRF, see below). - For satellites (orbits, antenna offsets etc.): Use "CNNN" where C is the GNSS code (G=GPS, R=GLONASS, E=Galileo) and NNN is the SVN number (GPS and Galileo) or GLONASS number. - For spherical harmonics CN, SN: Degree n of the coefficient	A4
Point Code	- For stations: A two character code identifying physical monument within a site. Typically has a code A, but could vary if the site has more than one monument. - For satellite antenna offsets: Frequency or linear combination for which phase center offsets are estimated. GPS: L1, L2, LC GLONASS: L1, L2, LC (LC: ionosphere-free linear combi-nation of L1 and L2) Galileo: L1, L5, L7, L8, L6 Following the RINEX definition: L1=E1, L5=E5a, L7=E5b, L8=E5a+E5b L6=E6 Galileo ionosphere-free linear combinations are to be identified as follows: 15: L1 and L5 linear combination 16: L1 and L6 linear combination 17: L1 and L7 linear combination 18: L1 and L8 linear combination 56: L5 and L6 linear combination ... etc. - For bias parameters: satellite ID L1, L2 for LAGEOS-1 or -2; LC for combined LAGEOS; E1, E2 for Etalon 1 or 2; EC for combined Etalon;	A2
Solution ID	- For stations: Character identifying the solution given for a point at a site. "----" applies to all. - For spherical harmonics CN, SN: Order m of the coefficient	A4
Observation Code.	A single character indicating the technique(s) used to arrive at the solutions obtained in this SINEX file. It should be consistent with the IERS convention.	A1

	This character code may be: C-Combined techniques used. D-DORIS, L-SLR, M-LLR, P-GNSS, R-VLBI.	

Comment:

For the official IERS sites the values of the 'Site Code' are listed in ftp://lareg.ensg.ign.fr/pub/itrf/iers_dir.sta

'Per year' means 365.25 days in this context.

3. Header Line (Mandatory)

Description

The header line must be the first line in a SINEX file.

Contents:

H_E_A_D_E_R___L_I_N_E		
Field	Description	Format
First Character	Single character '%' in column #1. No other character than '%' is allowed.	A1
Second Character	Single character '=' in column #2. Indicates 'resultant' solution. No other character than '=' is allowed.	A1
Document Type	Three characters 'SNX' in columns 3 to 5. Indicates that this is a SINEX document.	A3
Format Version	Four digits indicating the version of SINEX format used. '2.10' for this version.	1X,F4.2
File Agency Code	Identify the agency creating the file.	1X,A3
[Time]	Creation time of this SINEX file.	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Agency Code]	Identify the agency providing the data in the SINEX file	1X,A3
[Time]	Start time of the data used in the SINEX solution Value 00:000:00000 should be avoided in case of an analysis output (for a SINEX template it can be used).	1X,I2.2, 1H:,I3.3, 1H:,I5.5

[Time]	End time of the data used in the SINEX solution Value 00:000:00000 should be avoided in case of an analysis output (for a SINEX template it can be used).	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Observation Code]	Technique(s) used to generate the SINEX solution	1X,A1
Number of Est-timates	Number of parameters estimated in this SINEX file. Mandatory field.	1X,I5.5
[Constraint Code]	Single character indicating the constraint in the SINEX solution. Mandatory field.	1X,A1
Solution Contents	Solution types contained in this SINEX file. Each character in this field may be one of the following: S – all station parameters, i.e. station coordinates, station velocities, biases, geocenter, O - Orbits, E - Earth Orientation Parameter T – Troposphere, C – Celestial Reference Frame, A – Antenna parameters BLANK	6(1X,A1)
		79

Relationship with other blocks:

This line is duplicated as the resultant line of the INPUT/HISTORY block with the exception of its first character.

4. FILE/REFERENCE Block (Mandatory)

Description:

This block provides information on the Organization, point of contact, the software and hardware involved in the creation of the file.

Contents:

FILE REFERENCE DATA LINE		
Field	Description	Format
Information Type	Describes the type of information present in the next field. May take on the following values: 'DESCRIPTION' - Organization(s) gathering/altering the file contents. 'OUTPUT' - Description of the file contents. 'CONTACT' - Address of the	1X,A18

	relevant contact. e-mail	
	'SOFTWARE' - Software used to generate the file.	
	'HARDWARE' - Computer hardware on which above software was run.	
	'INPUT' - Brief description of the input used to generate this solution.	
	Any of the above fields may be and in any order.	
Information	Relevant information for the type indicated by the previous field.	1X,A60
		80

5. FILE/COMMENT Block (Optional)

Description:

This block can be used to provide general comments about the SINEX data file.

Contents:

FILE COMMENT DATA LINE		
Field	Description	Format
Comment	Any general comment providing relevant information about the SINEX file.	1X,A79
		80

6. INPUT/HISTORY Block (Recommended)

Description:

This block provides information about the source of the information used to create the current SINEX file.

Contents:

INPUT HISTORY DATA LINE		
Field	Description	Format
File Code	Only one of the following characters is permitted: '+' - This character indicates that the information that follows identify an input solution contributing to this SINEX file. '=' - This character indicates that the information that follows identify the output solution file.	1X,A1

Document Type	Three characters 'SNX' in columns 3 to 5. Indicates that this is a SINEX document.	A3
Format Version	Four digits indicating the version of SINEX format used. '2.01' for this version.	1X,F4.2
[Agency Code]	Identify the agency creating the file.	1X,A3
[Time]	Creation time of this SINEX file.	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Agency Code]	Identify the agency providing the data in the SINEX file.	1X,A3
[Time]	Start time of the data used in the SINEX solution.	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	End time of the data used in the SINEX solution.	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Observation Technique]	Technique(s) used to generate the SINEX solution.	1X,A1
Number of Est-timates	Number of parameters estimated in this SINEX file.	1X,I5.5
[Constraint Code]	Single digit indicating the constraint in the SINEX solution.	1X,A1
Solution Contents	Solution types contained in this SINEX file. Each character in this field may be one of the following: S – all station parameters, i.e. station coordinates, station velocities, biases, geocenter, O - Orbits, E - Earth Orientation Parameter T – Troposphere, C – Celestial Reference Frame, A – Antenna parameters BLANK	6(1X,A1)
		79

Comment:

The final data line "=" describes the current SINEX file and match the header line with the exception of the first character.

7. INPUT/FILES Block (Optional)

Description:

This block identify the input files (and the current SINEX file) and allow for a short comment to be added to describe those files.

Contents:

INPUT FILES DATA LINE		
Field	Description	Format
[Agency Code]	Agency creating the solution described in this data line.	1X,A3
[Time]	Time of creation of the input SINEX solution	1X,I2.2, 1H:,I3.3, 1H:,I5.5,
File Name	Name of the file containing the solution described in the current data line.	1X,A29
File Description	General description of the file referred to on this data line.	1X,A32
		80

Comments:

There must be exactly one INPUT/FILES data line for every INPUT/HISTORY data line. The final data line must describe this current SINEX file.

8. INPUT/ACKNOWLEDGEMENTS Block (Optional)

Description:

This block defines the agency codes contributing to the SINEX file.

Contents:

INPUT ACKNOWLEDGMENTS DATA LINE		
Field	Description	Format
[Agency Code]	Agency(ies) contributing to this SINEX file.	1X,A3
Agency Description	Description of agency code.	1X,A75
		80

9. NUTATION/DATA Block (Mandatory for VLBI)

Description:

This block contains the nutation model used in the analysis procedure.

Contents:

NUTATION DATA LINE		
Field	Description	Format
Nutation Code	Code for nutation reference: IAU1980 IERS1996 IAU2000a IAU2000b	1X,A8
Comments	General description of the nutation model used	1X,A70
		80

COMMENT:

It must be a generally accepted model which is accessible to all users.

10. PRECESSION/DATA Block (Mandatory for VLBI)

Description:

This block contains the precession model used in the analysis procedure.

Contents:

PRECESSION DATA LINE		
Field	Description	Format
Precess. Code	Code for precession reference: IAU1976 IERS1996	1X,A8
Comments	General description of the nutation model used	1X,A70
		80

COMMENT:

It must be a generally accepted model which is accessible to all users.

11. SOURCE/ID (Mandatory for VLBI)

Description:

This block contains information about the radio sources estimated in the analysis, especially the names used in ICRF and for IERS.

Contents:

RADIO SOURCE DATA LINE		
Field	Description	Format
Source Code	Call sign for a source	1X,A4

IERS des.	IERS designation of the radio source	1X,A8
ICRF des.	ICRF designation of the radio source	1X,A16
Comments	Comments or other names of the radio source	1X,A68
		80

12. SITE/ID Block (Mandatory)

Description:

This block provides general information for each site containing estimated parameters.

Contents:

SITE ID DATA LINE		
Field	Description	Format
[Site Code]	Call sign for a site.	1X,A4
[Point Code]	Physical monument used at a site	1X,A2
Unique Monument Identification	Unique alpha-nummeric monument identification. For ITRF purposes, it is a nine character DOMES/DOMEX number (five/six digits, followed by the single letter 'M' or 'S', followed by four/three digits)	1X,A9
[Observation Code]	Observation technique(s) used.	1X,A1
Station Description	Free-format description of the site, typically the town and/or country.	1X,A22
Approximate Longitude	Approximate longitude of the site in degrees(E/+), minutes and seconds.	1X,I3, 1X,I2, 1X,F4.1
Approximate Latitude	Approximate latitude of the site in degrees(NS/+-), minutes and seconds.	1X,I3, 1X,I2, 1X,F4.1
Approximate Height	Approximate height of the site in metres.	1X,F7.1
		75

Comments:

For DOMES numbers and station description as well as for Site Codes please refer to ftp://lareg.ensg.ign.fr/pub/itrf/iers_dir.sta

If a DOMES number is not available (e.g. for a new station), please ask Zuheir Altamimi for a DOMES number (altamimi@ensg.ign.fr).

Use the minus sign for negative approximate longitude or latitude only in the "degrees" component and don't repeat it in the "minutes" and "seconds" component.

Following the ISO6709 specification, the range of longitude should be [-180° +180°[.

13. SITE/DATA Block (Optional)

Description:

This block gives the relationship between the estimated station parameters in the SINEX file and in the input files.

Contents:

SITE DATA LINE		
Field	Description	Format
[Site Code]	Site Code for solved station coordinates.	1X,A4
[Point Code]	Point Code for solved station coordinates.	1X,A2
[Solution ID]	Solution number to which the input in this data line is referred to.	1X,A4
[Site Code]	Site Code from an input SINEX file	1X,A4
[Point Code]	Point code from an input SINEX file.	1X,A2
[Solution ID]	Solution Number for a Site/Point from an input SINEX file.	1X,A4
[Observation Code]	Observation Code for a Site/Point/ Solution Number from an input SINEX file.	1X,A1
[Time]	Time of start of data for the input SINEX file.	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	Time of end of data for the input SINEX file.	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Agency Code]	Creation Agency Code for the input SINEX file.	1X,A3

[Time]	Creation time for the input SINEX file.	1X,I2.2, 1H:,I3.3, 1H:,I5.5

Comment:

Times must refer to observation epochs.

14. SITE/RECEIVER Block (Mandatory for GNSS)

Description:

List the receiver used at each site during the observation period of interest.

Contents:

SITE RECEIVER DATA LINE		
Field	Description	Format
[Site Code]	Site code for which some parameters are estimated.	1X,A4
[Point Code]	Point Code at a site for which some parameters are estimated.	1X,A2
[Solution ID]	Solution Number at a Site/Point code for which some parameters are estimated.	1X,A4
[Observation Code]	Identification of the observation technique used.	1X,A1
[Time]	Time since the receiver has been operating at the Site/Point. Value 00:000:00000 indicates that the receiver has been operating at least since the "File Epoch Start Time".	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	Time until the receiver is operated at a Site/Point. Value 00:000:00000 indicates that the receiver has been operating at least until the "File Epoch End Time".	1X,I2.2, 1H:,I3.3, 1H:,I5.5
Receiver Type	Receiver Name & model.	1X,A20
Receiver Serial Number	Serial number of the receiver. Takes on value '-----' if unknown.	1X,A5
Receiver Firmware	Firmware used by this receiver during the epoch specified above. Takes on value '---------------'	1X,A11

	if unknown.	
		80

Comments:

- For IGS standard receiver names please refer to
  ftp://igscb.jpl.nasa.gov/igscb/station/general/rcvr_ant.tab

15. SITE/ANTENNA Block (Mandatory for GNSS)

Description:

List of antennas used at each site used in the SINEX file.

Contents:

SITE ANTENNA DATA LINE

Field	Description	Format
[Site Code]	Site code for which some parameters are estimated.	1X,A4
[Point Code]	Point Code at a site for which some parameters are estimated.	1X,A2
[Solution ID]	Solution Number at a Site/Point code for which some parameters are estimated.	1X,A4
[Observation Code]	Identification of the observation technique used.	1X,A1
[Time]	Time since the antenna has been installed at the Site/Point. Value 00:000:00000 indicates that the antenna has been installed at least since the "File Epoch Start Time".	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	Time until the antenna is installed at a Site/Point. Value 00:000:00000 indicates that the antenna has been installed at least until the "File Epoch End Time".	1X,I2.2, 1H:,I3.3, 1H:,I5.5
Antenna Type	Antenna name & model.	1X,A20
Antenna Serial Number	Serial number of the antenna. Takes on value '-----' if unknown.	1X,A5
		68

Comments:

- For IGS standard antenna names please refer to
  ftp://igscb.jpl.nasa.gov/igscb/station/general/rcvr_ant.tab

16a. SITE/GPS_PHASE_CENTER Block (Mandatory for GPS)

Description:

List of GPS phase center offsets for the antennas described in the Site Antenna block. The offset is given from the Antenna Reference Point (ARP) to the L1 and L2 phase centers respectively.

Contents:

GPS PHASE CENTER DATA LINE		
Field	Description	Format
Antenna Type	Antenna name & model.	1X,A20
Antenna Serial Number	Serial number of the antenna. Takes on value '-----' if the phase center offsets apply to all antennas of the same type.	1X,A5
L1 Phase Center Up Offset	Up(+) offset from the ARP to the L1 phase center in meters.	1X,F6.4
L1 Phase Center North Offset	North(+) offset from the ARP to the L1 phase center in meters.	1X,F6.4
L1 Phase Center East Offset	East(+) offset from the ARP to the L1 phase center in meters.	1X,F6.4
L2 Phase Center Up Offset	Up(+) offset from the ARP to the L2 phase center in meters.	1X,F6.4
L2 Phase Center North Offset	North(+) offset from the ARP to the L2 phase center in meters.	1X,F6.4
L2 Phase Center East Offset	East(+) offset from the ARP to the L2 phase center in meters.	1X,F6.4
Antenna Calibration Model	Name of the antenna model used in the correction of the observations for phase center variations.	1X,A10
		80

Comments:

For IGS purposes see the IGS Central Bureau Information System for ARPs and antenna phase center offsets:
directory: ftp://igscb.jpl.nasa.gov/igscb/station/general
files: antenna.gra, igs_01.pcv and igs_01.atx respectively

If the phase center offsets for one antenna type (antenna name and the given model) are the same for all antenna serial numbers, it is enough to store only one data line (with '-----' for the 'Antenna Serial Number') in this block for each antenna type that appears in the SITE/ANTENNA block.

16b. SITE/GAL_PHASE_CENTER Block (Mandatory for Galileo)

Description:

List of Galileo phase center offsets for the antennas described in the Site Antenna block. The offset is given from the Antenna Reference Point (ARP) to the appropriate phase centers. Three lines per antenna are required:
- line 1: frequencies L1 and L5
- line 2: frequencies L6 and L7
- line 3: frequency L8

Contents:

GAL PHASE CENTER DATA LINE 1

Field	Description	Format
Antenna Type	Antenna name & model.	1X,A20
Antenna Serial Number	Serial number of the antenna. Takes on value '-----' if the phase center offsets apply to all antennas of the same type.	1X,A5
L1 Phase Center Up Offset	Up(+) offset from the ARP to the L1 phase center in meters.	1X,F6.4
L1 Phase Center North Offset	North(+) offset from the ARP to the L1 phase center in meters.	1X,F6.4
L1 Phase Center East Offset	East(+) offset from the ARP to the L1 phase center in meters.	1X,F6.4
L5 Phase Center Up Offset	Up(+) offset from the ARP to the L5 phase center in meters.	1X,F6.4
L5 Phase Center North Offset	North(+) offset from the ARP to the L5 phase center in meters.	1X,F6.4
L5 Phase Center East Offset	East(+) offset from the ARP to the L5 phase center in meters.	1X,F6.4
Antenna Calibration Model	Name of the antenna model used in the correction of the observations for phase center variations.	1X,A10
		80

GAL PHASE CENTER DATA LINE 2

Field	Description	Format
Antenna Type	Antenna name & model.	1X,A20
Antenna Serial Number	Serial number of the antenna. Takes on value '-----' if the phase center offsets apply to all antennas of the same type.	1X,A5

L6 Phase Center Up Offset	Up(+) offset from the ARP to the L6 phase center in meters.	1X,F6.4
L6 Phase Center North Offset	North(+) offset from the ARP to the L6 phase center in meters.	1X,F6.4
L6 Phase Center East Offset	East(+) offset from the ARP to the L6 phase center in meters.	1X,F6.4
L7 Phase Center Up Offset	Up(+) offset from the ARP to the L7 phase center in meters.	1X,F6.4
L7 Phase Center North Offset	North(+) offset from the ARP to the L7 phase center in meters.	1X,F6.4
L7 Phase Center East Offset	East(+) offset from the ARP to the L7 phase center in meters.	1X,F6.4
Antenna Calibration Model	Name of the antenna model used in the correction of the observations for phase center variations.	1X,A10
		80

GAL PHASE CENTER DATA LINE 3

Field	Description	Format
Antenna Type	Antenna name & model.	1X,A20
Antenna Serial Number	Serial number of the antenna. Takes on value '-----' if the phase center offsets apply to all antennas of the same type.	1X,A5
L8 Phase Center Up Offset	Up(+) offset from the ARP to the L8 phase center in meters.	1X,F6.4
L8 Phase Center North Offset	North(+) offset from the ARP to the L8 phase center in meters.	1X,F6.4
L8 Phase Center East Offset	East(+) offset from the ARP to the L8 phase center in meters.	1X,F6.4
	Empty field; Room for one more frequency	3(1X,F6.4)
Antenna Calibration Model	Name of the antenna model used in the correction of the observations for phase center variations.	1X,A10
		80

Comments:

If the phase center offsets for one antenna type (antenna name and the given model) are the same for all antenna serial numbers, it is enough to store only one group of three data lines (with '-----' for the 'Antenna Serial Number') in this block for each antenna type that appears in the SITE/ANTENNA block.

17. SITE/ECCENTRICITY Block (Mandatory)

Description:

List of antenna eccentricities from the Marker to the Antenna Reference Point (ARP) or to the intersection of axis.

Contents:

SITE ECCENTRICITY DATA LINE		
Field	Description	Format
[Site Code]	Site code for which some parameters are estimated.	1X,A4
[Point Code]	Point Code at a site for which some parameters are estimated.	1X,A2
[Solution ID]	Solution ID at a Site/Point code for which some parameters are estimated.	1X,A4
[Observation Code]	Identification of the observation technique used.	1X,A1
[Time]	Time since the antenna has been installed at the Site/Point. Value 00:000:00000 indicates that the antenna has been installed at least since the "File Epoch Start Time".	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	Time until the antenna is installed at a Site/Point. Value 00:000:00000 indicates that the antenna has been installed at least until the "File Epoch End Time".	1X,I2.2, 1H:,I3.3, 1H:,I5.5
Eccentricity Reference System	Reference system used to describe vector distance from monument benchmark to the antenna reference point or intersection of axis: 'UNE' - Local reference system Up, North, East. 'XYZ' - Cartesian Reference System X, Y, Z. All units are in meters.	1X,A3
Up / X Eccentricity	Up / X offset from the marker to the Antenna reference point (ARP).	1X,F8.4

North / Y Eccentricity	North/Y offset from the marker to the Antenna reference point (ARP).	1X,F8.4
East / Z Eccentricity	East/Z offset from the marker to the Antenna reference point (ARP).	1X,F8.4
		72

Comments:

- At the moment the local ties used in the ITRF2000 primary combination are only available throughout a login/password ftp access. To get access to these values please contact Zuheir Altamimi (altamimi@ensg.ign.fr).

- An older (March 23, 1999) listing of the official values for IERS sites is available at
  ftp://lareg.ensg.ign.fr/pub/itrf/iers.ecc

- For GPS (antenna heights) you can refer to the daily generated IGS SINEX template:
  ftp://igscb.jpl.nasa.gov/pub/station/general/igs.snx

- For VLBI solutions you can use
  http://gemini.gsfc.nasa.gov/solve_save/ECCDAT.ecc

- The official ILRS eccentricity files (in SINEX format) are
  ftp://cddisa.gsfc.nasa.gov/pub/slrocc/ecc_une.snx
  for eccentricities in Up, North, East
  and
  ftp://cddisa.gsfc.nasa.gov/pub/slrocc/ecc_xyz.snx
  for eccentricities in X, Y, Z

18. SATELLITE/ID Block (Recommended for GNSS, if available)

Description:

List of GNSS satellites used in the SINEX file.

Contents:

SATELLITE ID DATA LINE		
Field	Description	Format
[Site Code]	Satellite code "CNNN": C - GNSS code NNN – SVN or GLONASS number	1X,A4
PRN	GPS and Galileo: Pseudo-random noise number GLONASS: Slot number	1X,A2
COSPAR ID	ID assigned by the World Data Center for Satellite Information at the NASA Goddard Space Flight Center following the spacecraft launch. COSPAR ID format: YYYY-XXXA YYYY - year of when the launch vehicle was put in orbit XXX - sequential launch vehicle number for that year A - alpha numeric sequence number within a launch	1X,A9

[Observation Code]	Observation technique(s) used.	1X,A1
[Time]	Time since the satellite has been launched. Value 00:000:00000 indicates that the satellite has been launched at least since the "File Epoch Start Time".	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	Time until the satellite is decommissioned from active service. Value 00:000:00000 indicates that the satellite has been active at least until the "File Epoch End Time".	1X,I2.2, 1H:,I3.3, 1H:,I5.5
Antenna Type	Strict IGS rcvr_ant.tab satellite antenna name.	1X,A20

Comments:

- For GPS information (SVN, PRN, launch date, etc.) please refer to
  ftp://tycho.usno.navy.mil/pub/gps/gpsb1.txt and
  ftp://tycho.usno.navy.mil/pub/gps/gpsb2.txt

- For GLONASS information (GLONASS number, slot number, launch date, etc.) please refer to
  http://www.glonass-center.ru/hist_e.html

- For COSPAR IDs please refer to
  http://www.aiub.unibe.ch/download/BSWUSER50/GEN/SATELLIT. or
  http://ilrs.gsfc.nasa.gov/satellite_missions/list_of_satellites/glonass/

- For IGS standard antenna names please refer to
  ftp://igscb.jpl.nasa.gov/igscb/station/general/rcvr_ant.tab

19. SATELLITE/PHASE_CENTER Block (Mandatory for GNSS, if satellite antenna offsets are not estimated)

Description:

List of GNSS satellite antenna phase center corrections. The antenna offsets are given from the center of mass (CM). More than one line per satellite is necessary, if the satellite transmits on more than two frequencies.

Contents:

SATELLITE PHASE CENTER DATA LINE		
Field	Description	Format
[Site Code]	Satellite code "CNNN": C - GNSS code NNN – SVN or GLONASS number	1X,A4
Frequency Code	A single character indicating the frequency for which the phase center offset is given within the following three data fields. GPS: 1 – L1	1X,A1

	2 – L2 5 – L5 GLONASS: 1 – L1 2 – L2 5 – L5 Galileo (following RINEX 3.00): 1 – E1 5 – E5a 6 – E6 7 – E5b 8 – E5a + E5b	
Phase Center Z Offset	Z(+) offset from the CM to the phase center in meters.	1X,F6.4
Phase Center X Offset	X(+) offset from the CM to the phase center in meters.	1X,F6.4
Phase Center Y Offset	Y(+) offset from the CM to the phase center in meters.	1X,F6.4
Frequency Code	A single character indicating the frequency for which the phase center offset is given within the following three data fields. GPS: 1 – L1 2 – L2 5 – L5 GLONASS: 1 – L1 2 – L2 5 – L5 Galileo (following RINEX 3.00): 1 – E1 5 – E5a 6 – E6 7 – E5b 8 – E5a + E5b	1X,A1
Phase Center Z Offset	Z(+) offset from the CM to the phase center in meters.	1X,F6.4
Phase Center X Offset	X(+) offset from the CM to the phase center in meters.	1X,F6.4
Phase Center Y Offset	Y(+) offset from the CM to the phase center in meters.	1X,F6.4
Antenna Calibration Model	Name of the antenna model used in the correction of the observations for phase center variations (PCVs).	1X,A10
PCV Type	Phase center variation type A – absolute values R – relative values	1X,A1
PCV Model Application	F – full PCV model applied E – elevation-dependent PCVs applied only	1X,A1

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Comments:

For IGS purposes see the IGS Central Bureau Information System for satellite antenna phase center offsets:
directory: ftp://igscb.jpl.nasa.gov/igscb/station/general
file: igs_01.atx

20. SOLUTION/EPOCHS Block (Mandatory)

Description:

List of solution epoch for each Site Code/Point Code/Solution Number/Observation Code (SPNO) combination.

Contents:

SOLUTION EPOCHS DATA LINE

Field	Description	Format
[Site Code]	Site code for which some parameters are estimated.	1X,A4
[Point Code]	Point Code at a site for which some parameters are estimated.	1X,A2
[Solution ID]	Solution Number at a Site/Point code for which some parameters are estimated.	1X,A4
[Observation Code]	Identification of the observation technique used.	1X,A1
[Time]	Start time for which the solution identified (SPNO) has observations	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	End time for which the solution identified (SPNO) has observations	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	Mean time of the observations for which the solution (SPNO) is derived.	1X,I2.2, 1H:,I3.3, 1H:,I5.5

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21. BIAS/EPOCHS Block (Mandatory if bias parameters are included)

Description:

List of epochs of bias parameters for each Site Code/Point Code/Solution Number/Bias Type (SPNB) combination for which a bias parameter is solved.

Contents:

BIAS EPOCHS DATA LINE

Field	Description	Format
[Site Code]	Site code for which some biases are estimated (station ID)	1X,A4
[Point Code]	satellite ID for which some biases are estimated: e.g. L1, L2 for LAGEOS-1 and -2 respectivly	1X,A2
[Solution ID]	sequential number of the bias for this particular station (if just one bias is solved for a particular station, this parameter remains "1").	1X,A4
Bias Type	Specification of the type of bias: R - range bias T - time bias S - scale bias Z - troposphere bias at zenith	1X,A1
[Time]	Epoch of 1st observation of the solution identified (SPNB)	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	Epoch of last observation of the solution identified (SPNB)	1X,I2.2, 1H:,I3.3, 1H:,I5.5
[Time]	Weighted mean time of the observations for which the solution (SPNB) is derived.	1X,I2.2, 1H:,I3.3, 1H:,I5.5

22. SOLUTION/STATISTICS Block (Recommended if available)

Description:

Statistical information about the solution contained in the SINEX file.

Contents:

SOLUTION_STATISTICS_LINE		
Field	Description	Format
Information Type	Describes the type of information present in the next field. May take on the following values: 'NUMBER OF OBSERVATIONS' # of observations used in the adjustment. 'NUMBER OF UNKNOWNS' # of unknowns solved in the adjustment. 'SAMPLING INTERVAL (SECONDS)' Interval in seconds between	1X,A30

	successives observations.	
	'SQUARE SUM OF RESIDUALS (VTPV)'	
	Sum of squares of residuals.	
	(V'PV); V - resid. vector;	
	P - weight matrix	
	'PHASE MEASUREMENTS SIGMA'	
	Sigma used for the phase	
	measurements.	
	'CODE MEASUREMENTS SIGMA'	
	Sigma used for the code (pseudo-	
	range) measurements.	
	'NUMBER OF DEGREES OF FREEDOM'	
	# of observations minus the	
	# of unknowns	
	(df)	
	'VARIANCE FACTOR'	
	Sum of squares of residuals	
	divided by the degrees of	
	freedom (V'PV/df). Equivalent	
	to Chi-squared/df.	
	'WEIGHTED SQUARE SUM OF O-C'	
	Sum of squares of the vector	
	'observed minus computed':	
	(o-c)'P(o-c)	
	with P - weigth matrix	
Information	Relevant information for the type indicated by the previous field.	1X,F22.15

Comments:

The mentioned 'Information Types' may be in any order but the name of the fields should be identical to the names listed above.

Note that the NUMBER OF UNKNOWNS contains all parameters of the adjustment, i.e., not only the parameters stored in the SINEX file but as well all the pre-eliminated parameters.

The NUMBER OF OBSERVATIONS should contain only the real observations and not the pseudo-observations used for constraining.

In principle the estimated variance-covariance matrix should be normalized / multiplied by the VARIANCE FACTOR of this statistic block.

23. SOLUTION/ESTIMATE Block (Mandatory)

Description:

Estimated parameters.

Contents:

SOLUTION_ESTIMATE_DATA_LINE		
Field	Description	Format
Estimated Parameters Index	Index of estimated parameters. values from 1 to the number of parameters.	1X,I5
[Parameter Type]	Identification of the type of parameter.	1X,A6

[Site Code]	Site code for which the parameter is estimated.	1X,A4
[Point Code]	Point Code for which the parameter is estimated.	1X,A2
[Solution ID]	Solution ID at a Site/Point code for which the parameter is estimated.	1X,A4
[Time]	Epoch at which the estimated parameter is valid. For bias parameters the beginning of the pass (identical to the BIAS/EPOCHS block).	1X,I2.2, 1H:,I3.3, 1H:,I5.5
Parameter Units	Units used for the estimates and sigmas. The notations are: m (metres), m/y (metres per year), m/s2 (metres per second**2), ppb (parts per billion), ms (milliseconds), msd2 (milliseconds per day**2), mas (milli-arc-seconds), ma/d (milli-arc-seconds / day), rad (radians), rd/y (radians per year), rd/d (radians per day).	1X,A4
[Constraint Code]	Constraint applied to the parameter.	1X,A1
Parameter Estimate	Estimated value of the parameter.	1X,E21.15
Parameter Standard Deviation	Estimated standard deviation for the parameter.	1X,E11.6
		80

Comments:

For the demanded units of the estimated parameters and their standard deviation please refer to the list of possible parameter types (2. Data Structure).
'Per year' means 365.25 days in this context.

24. SOLUTION/APRIORI Block (Mandatory)

Description:

Apriori information for estimated parameters, either the used apriori values for the adjustment or the parameters of a Helmert Transformation for applied inner constraints with the constraint given in the field 'Standard Deviation'.

Contents:

SOLUTION/APRIORI DATA LINE		
Field	Description	Format

Parameter Index	Index of apriori parameters.	1X,I5
[Parameter Type]	Identification of the type of parameter. For apriori values of estimated parameters see parameter list above; For inner constraints: TX - Translation in X-direction m TY - Translation in Y-direction m TZ - Translation in Z-direction m RX - Rotation around X-axis mas RY - Rotation around Y-axis mas RZ - Rotation around Z-axis mas SC - Scale ppb TXR – Rate for translation in X-direction m/y TYR – Rate for translation in Y-direction m/y TZR – Rate for translation in Z-direction m/y RXR – Rate for rotation around X-axis mas/y RYR – Rate for rotation around Y-axis mas/y RZR – Rate for rotation around Z-axis mas/y SCR – Rate for scale ppb/y	1X,A6
[Site Code]	Site code with apriori parameter estimate. ---- for inner constraints	1X,A4
[Point Code]	Point Code with apriori parameter estimate. -- for inner constraints	1X,A2
[Solution ID]	Solution ID at a Site/Point code with apriori parameter estimate. ---- for inner constraints	1X,A4
[Time]	Epoch at which the apriori parameter or the inner constraint is valid.	1X,I2.2, 1H:,I3.3, 1H:,I5.5
Parameter Units	Units used for the aprioris and sigmas. For the demanded units look at SOLUTION/ESTIMATE block. For the inner constraints the units should be: m for translations, mas for rotations, ppb for scale, m/y for translation rates, ma/y for rotation rates, pb/y for scale rates	1X,A4
[Constraint Code]	Constraint applied to the parameter. If inner constraints are applied:	1X,A1

	1 for contributing stations	
Parameter Apriori	Apriori value of the parameter or transformation parameter for the inner constraint.	1X,E21.15
Parameter Standard Deviation	Apriori standard deviation for the parameter or applied inner constraint.	1X,E11.6
		80

Comments:

If inner constraints are applied to the solution (i.e. parameters like TX, TY, TZ, RX,... are included) the stations contributing to these inner constraints should be listed with a '1' in the field 'Constraint Code' in this SOLUTION/APRIORI block.

25. SOLUTION/MATRIX_ESTIMATE Block (Mandatory)

Description:

The Estimate Matrix can be stored in an Upper or Lower triangular form. Only the Upper or Lower portion needs to be stored because the matrix is always symmetrical.
The matrix contents can be:
CORR - Correlation Matrix
COVA - Covariance Matrix
INFO - Information Matrix (of Normals), i.e. COVA^(-1)
The distinction between the form and its contents is given by the title block which must take one of the following forms:

```
SOLUTION/MATRIX_ESTIMATE L CORR
SOLUTION/MATRIX_ESTIMATE U CORR
SOLUTION/MATRIX_ESTIMATE L COVA
SOLUTION/MATRIX_ESTIMATE U COVA
SOLUTION/MATRIX_ESTIMATE L INFO
SOLUTION/MATRIX_ESTIMATE U INFO
```

Contents:

SOLUTION/MATRIX_ESTIMATE/DATA/LINE		
Field	Description	Format
Matrix Estimate Row Number	Row index for the Matrix Estimate. It must match the parameter index in the SOLUTION/ESTIMATE block for the same parameter.	1X,I5
Matrix Estimate Column Number	Column index for the Matrix Estimate. It must match the parameter index in the SOLUTION/ESTIMATE block for the same parameter.	1X,I5
First Matrix Estimate Element	Matrix element at the location (Row Number , Column Number).	1X,E21.14
Second Matrix Estimate Element	Matrix element at the location (Row Number , Column Number + 1).	1X,E21.14
Third Matrix	Matrix element at the location	1X,E21.14

Estimate Element	(Row Number , Column Number + 2).	78

Comment:

The Matrix Estimate Row/Column Number correspond to the Estimated Parameters Index in the SOLUTION/ESTIMATE block.
If the CORR matrix is used, standard deviations must be stored in the diagonal elements instead of 1.000.
Missing elements in the matrix are assumed to be zero (0); consequently, zero elements may be omitted to reduce the size of this block.

NOTE: The same scale (variance) factor MUST be used for both MATRIX_ESTIMATE and MATRIX_APRIORI, as well as for the standard deviations in the ESTIMATE and APRIORI Blocks. This scale factor should be stored as 'Variance Factor' in the SOLUTION/STATISTICS block.

If you use the INFO type this block should contain the constrained normal equation matrix of your least square adjustment.

26. SOLUTION/MATRIX_APRIORI Block (Recommended/Mandatory)

Description:

The Apriori Matrix can be stored in an Upper or Lower triangular form. Only the Upper or Lower portion needs to be stored because the matrix is always symmetrical. Mandatory if any significant constraint have been applied to the SOLUTION/ESTIMATE.
The matrix contents can be:
CORR - Correlation Matrix
COVA - Covariance Matrix
INFO - Information Matrix (of Normals), i.e. COVA^(-1)
The distinction between the form and its contents is given by the title block which must take one of the following forms:

```
SOLUTION/MATRIX_APRIORI L CORR
SOLUTION/MATRIX_APRIORI U CORR
SOLUTION/MATRIX_APRIORI L COVA
SOLUTION/MATRIX_APRIORI U COVA
SOLUTION/MATRIX_APRIORI L INFO
SOLUTION/MATRIX_APRIORI U INFO
```

Contents:

SOLUTION MATRIX APRIORI DATA LINE		
Field	Description	Format
Matrix Apriori Row Number	Row index for the Matrix Apriori. It must match the parameter index in the SOLUTION/APRIORI block for the same parameter.	1X,I5
Matrix Apriori Column Number	Column index for the Matrix Apriori. It must match the parameter index in the SOLUTION/APRIORI block for the same parameter.	1X,I5
First Matrix Estimate Element	Matrix element at the location (Row Number , Column Number).	1X,E21.16
Second Matrix Estimate Element	Matrix element at the location (Row Number , Column Number + 1).	1X,E21.16

Third Matrix Estimate Element	Matrix element at the location (Row Number , Column Number + 2).	1X,E21.16
		78

Comment:

The Matrix Apriori Row/Column Number correspond to the Apriori Parameters Index in the SOLUTION/APRIORI block. If the apriori constraint matrix is diagonal and no loss of significant digits occurs by using the Parameter Standard Deviation in the SOLUTION/APRIORI block, then, this block becomes redundant.
If the CORR matrix is used, Standard deviations must be stored in the diagonal elements instead of 1.000.
Missing elements in the matrix are assumed to be zero (0); consequently, zero elements may be omitted to reduce the size of this block.

NOTE: The same scale (variance) factor MUST be used for both MATRIX_ESTIMATE and MATRIX_APRIORI, as well as for the standard deviations in the ESTIMATE and APRIORI Blocks. This scale factor should be stored as 'Variance Factor' in the SOLUTION/STATISTICS block.

If you use the INFO type this block should contain the normal equation matrix of the constraints applied to your solution in SOLUTION/ESTIMATE.

27. SOLUTION/NORMAL_EQUATION_VECTOR Block (Mandatory for normal equations)

Description:

If the SINEX file shall provide the normal equation directly this block is mandatory and contains the vector of the right hand side of the unconstrained (reduced) normal equation.

Contents:

SOLUTION__N_O_R_M_A_L___E_Q_U_A_T_I_O_N___V_E_C_T_O_R___DATA_LINE_		
__Field_____	_____Description_____	___Format_____
Estimated Parameters Index	Index of estimated parameters. Values from 1 to the number of parameters. It must match the parameter index in the block SOLUTION/ESTIMATE for the same parameter.	1X,I5
[Parameter Type]	Identification of the type of parameter.	1X,A6
[Site Code]	Site code for which the parameter is estimated.	1X,A4
[Point Code]	Point Code for which the parameter is estimated.	1X,A2
[Solution ID]	Solution ID at a Site/Point code for which some parameters are estimated.	1X,A4
[Time]	Epoch at which the estimated parameter is valid. For bias parameters the beginning	1X,I2.2, 1H:,I3.3, 1H:,I5.5

	of the pass (identical to the BIAS/EPOCHS block).	
Parameter Units	see SOLUTION/ESTIMATE	1X,A4
[Constraint Code]	Constraint applied to the parameter.	1X,A1
Right hand side of normal equation	Value of the right hand side of the normal equation for the corresponding parameter.	1X,E21.15
		68

Comment:

The indices correspond to the indices of the SOLUTION/ESTIMATE block.

28. SOLUTION/NORMAL_EQUATION_MATRIX Block (Mandatory for normal equations)

Description:

This block is mandatory if the normal equation is to be provided directly in the SINEX file.
The block should contain the original (reduced) normal equation matrix (i.e., without constraints).
The normal equation matrix can be stored in an Upper or Lower triangular form. Only the Upper or Lower portion needs to be stored because the matrix is always symmetrical. The distinction between the forms is given by the title block which must take one of the following forms:

SOLUTION/NORMAL_EQUATION_MATRIX L
SOLUTION/NORMAL_EQUATION_MATRIX U

Contents:

SOLUTION__N_O_R_M_A_L___E_Q_U_A_T_I_O_N___M_A_T_R_I_X___DATA_LINE_		
__Field_____	_____Description_____	___Format_____
NEQ-Matrix Row Number	Row index for the normal equation matrix. It must match the parameter index in the SOLUTION/ ESTIMATE block for the same parameter.	1X,I5
NEQ-Matrix Column Number	Column index for the normal equation matrix. It must match the parameter index in the SOLUTION/ ESTIMATE block for the same parameter.	1X,I5
First Matrix Element	Matrix element at the location (Row Number , Column Number).	1X,E21.14
Second Matrix Element	Matrix element at the location (Row Number , Column Number + 1).	1X,E21.14
Third Matrix Element	Matrix element at the location (Row Number , Column Number + 2).	1X,E21.14

		78

Comment:

The NEQ-Matrix Row/Column Number correspond to the Estimated Parameters Index in the SOLUTION/ESTIMATE block.
Missing elements in the matrix are assumed to be zero (0); consequently, zero elements may be omitted to reduce the size of this block.

29. Footer Line (Mandatory)

Description:

Marks the end of the SINEX file.

Contents:

FOOTER LINE		
Field	Description	Format
End of SINEX	The seven characters %ENDSNX at the beginning of the last line mark the end of the SINEX file.	A7
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SINEX - Solution (Software/technique) INdependent EXchange Format
Version 2.10 (September 15, 2006)

A P P E N D I X II

S U M M A R Y O F F O R M U L A S A N D T H E I R C O N N E C T I O N T O S I N E X

This document gives a short summary of the basic formulas used for least squares adjustment and it gives instructions which vector or matrix of the normal equation system belongs to the individual SINEX blocks.

SUMMARY OF LEAST SQUARES ADJUSTMENT FORMULAS

You have n_obs linearized observation equations

(1) $v = A\,dx - l$

where
n_obs number of observations
v residual vector
A Jacobian matrix
dx corrections for the unknowns x concerning the apriori values x0

i.e. x = x0 + dx

with

n_unk	number of unknowns
l	vector 'observed' minus 'computed with apriori values'.
P	denotes the weight matrix for the observations.

The goal of least square adjustment is to minimize the square sum of residuals:

(2) v' P v = min

where v' is the transposed vector of v.

This condition leads to the so called normal equation

(3) A' P A dx = A' P l

with normal equation matrix

(4) N = A' P A

and the vector of the right hand side of the normal equation

(5) b = A' P l .

The resulting unknown parameters can be determined with

(6) x = x0 + inv(A' P A) A' P l = x0 + inv(N) b

where inv stands for the inverse matrix and x0 are the apriori values.

The residuals can be computed with equation (1) and the aposteriori variance factor is then

(7) s0 = (v' P v) / (n_obs - n_unk) .

The weighted square sum o fthe vector l (= observed minus computed) can be obtained with

(8) l'Pl = v'Pv + dx' b
= v'Pv + dx' A' P l .

The variance-covariance matrix of the unknowns results in

(9) K = s0 inv(N).

If you introduce constraints as pseudo-observations with n_constr linearized observation equations

(10) v_c = H dx - h

with

n_constr	number of constraints as pseudo-observations
v_c	residuals over the constraints
H	Jacobian matrix for pseudo-observation equations
h	vector 'observed' minus 'computed' for the constraints.

P_c denotes the weight matrix for your pseudo-observations.

The least square methods lead to the normal equation for the pseudo-observations

(11) H' P_c H dx = H' P_c h

with normal equation matrix of constraints

(12) N_constr = H' P_c H

and vector of the right hand side of normal equation for constraints

(13) b_constr = H' P_c h.

The complete normal equation system for the constrained solution can easily be computed:

(14) (A' P A + H' P_c H) dx = A' P l + H' P_c h

with the constrained normal equation matrix

(15) N_total = A' P A + H' P_c H = N + N_constr

and the vector of the right hand side of the constrained normal equation system

(16) b_total = A' P l + H' P_c h = b + b_constr .

The unknown parameters of the constrained solution can be computed with

(17) x_c = x0 + inv(N_total) b_total .

Ater computing the residuals over the constraints with equation (10) the weighted square sum of residuals of the constrained normal equation system can be obtained with

(18) v'Pv + v_c' P_c v_c

and the number of degrees of freedom of the constrained normal equation system is

(19) dof = n_obs + n_constr – n_unk .

The aposteriori variance-factor for the constrained normal equation system is then

(20) s0_c = (v' P v + v_c' P_c v_c) / dof .

The variance-covariance matrix for the unknowns of this constrained normal equation system can be computed with

(21) K_xx = s0_c inv(N_total)

And the variance-covariance matrix for the constraints is

(22) K_constr = s0_c inv(N_constr) .

IMPLEMENTATION IN SINEX

The different elements belonging to the normal equations can be stored in SINEX files in the following way:

SOLUTION/STATISTICS block:

```
      n_unk                    = NUMBER OF UNKNOWNS
      n_obs                    = NUMBER OF OBSERVATIONS
 (20) s0_c                     = VARIANCE FACTOR
 (18) v' P v + v_c' P_c v_c    = SQUARE SUM OF RESIDUALS (VTPV)
 (19) dof                      = NUMBER OF DEGREES OF FREEDOM
```

SOLUTION/ESTIMATE block:

```
 (17) x_c    in field "Parameter Estimate"
```

SOLUTION/APRIORI block:

```
      x0  in field "Parameter Apriori"
```

SOLUTION/MATRIX_ESTIMATE block:

```
 (21) Type COVA:  K_xx
      Type CORR:  correlation matrix of K_xx
 (15) Type INFO:  N_total  =  N + N_constr
```

```
SOLUTION/MATRIX_APRIORI block:
 (22) Type COVA:  K_constr
      Type CORR:  correlation matrix of K_constr
 (12) Type INFO:  N_constr


SOLUTION/NORMAL_EQUATION_VECTOR block:
 (5)  b  =  A' P l


SOLUTION/NORMAL_EQUATION_MATRIX block:
 (4)  N  =  A' P A
```